UNIVERSITY OF SWAZILAND FACULTY OF SCIENCE DEPARTMENT OF ELECTRICAL AND ELECTRONICS ENGINEERING

MAIN EXAMINATION 2009

TITTLE OF PAPER: SIGNALS 1

COURSE CODE: E342

TIME ALLOWED: THREE HOURS

INSTRUCTIONS:

- 1. Answer any four of the following five questions.
- 2. Each question carries 25 marks
- 3. Marks for different sections are shown in the right hand margin

This paper has 6 pages including this page

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- Define the following terms: A)
 - i) periodic signal,

(2marks)

ii) discrete-time signal.

(2marks)

- For the following signals a) to e) below, B)
 - $x(t) = 4\cos(5\pi t)$ a)
 - $x(t) = 4\cos(5\pi t \pi/4)$ b)
 - $x(t) = 4u(t) + 2\sin(3t)$ c)
 - $x[n] = 4\cos(\pi n)$ d)
 - $x[n] = 4\cos(\pi n 2)$ e)
 - State whether the signal is periodic (if periodic, give period) i.

(5marks)

(6 marks)

- ii. Sketch the signals. (Scale your time axis so that a sufficient amount of the signal is being plotted). (10marks)
- C) Give an expression for the signals shown in Figure 1a and Figure 1b.

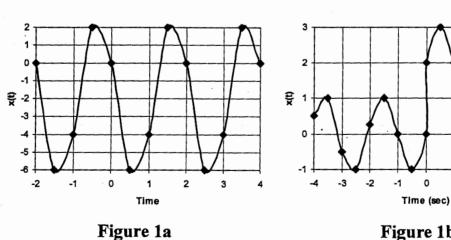


Figure 1b

Figure 1

- A) Define the terms:
 - i) signal sampling and (2 marks)
 - ii) sampling period. (2 marks)
- B) (i) State the sampling theorem and explain the term aliasing error.

 (4 marks)
 - (ii) Given two signals $a(t) = \cos \omega_0 t$ and $b(t) = \cos(\omega_0 + \omega_s)t$, where $\omega_s = 2\pi f_s$ is the sampling frequency in rad/s. Show that signals a(t) and b(t) are aliased. (5 marks)
 - iii) A Compact Disc (CD) system has a sample rate of 44 kHz. What is the highest frequency that can be sampled without aliasing?

 (2 marks)
 - iv) Samples are to be taken from a record of a continuous-time signal of duration 100 ms. The signal contains sinusoidal components with frequencies up to 250 Hz. Determine the minimum number of samples that would be sufficient to give a complete representation of the signal. (4 marks)
- C) Consider a rectangular pulse signal of height A and duration T centered at a point in time $t = t_0 > T$. Sketch the signal waveform in the time domain and obtain an analytic representation in terms of the rect() function and verify that it is correct. (6 marks)

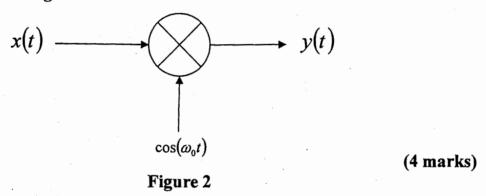
a) Determine whether the following signal processing operations i) to iv) are linear or non linear.

$$y[n] = \frac{1}{N} \sum_{n=0}^{N-1} x[n]$$
 (2 marks)

ii)
$$y[n] = \sqrt{x[n]}$$
 (2 marks)

iii)
$$y(t) = 2x^2(t)$$
 (2 marks)

iv) A system that performs modulation of a carrier signal $\cos(\omega_0 t)$ with an input signal x(t) to produce an output y(t) as shown in figure 2.



- b) (i) Explain the term "Time-Invariant" system. (2 marks)
 - (ii) Illustrate how you would test for a system's time-invariance.

(3 marks)

iii) Explain the term "Linear system" and illustrate how you would test for a system's linearity.

(4 marks)

c) Distinguish between power and energy signals and give an example of each. (6 marks)

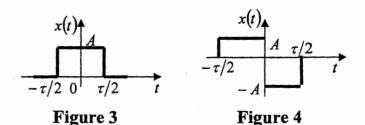
- A) (i) Define the unit-sample sequence $\delta[n]$ and show how it can be used to express any sequence as the sum of scaled and delayed unit-sample sequences. (4 marks)
 - (ii) Express the sequence given by x[n] = [1,1,1,1,0,0,0,....] in terms of the unit-sample sequence (2 marks)
 - iii) By using a property of the delta function $\delta(t)$, evaluate the integral $\int_{-\infty}^{\infty} f_1(t) \times f_2(t) dt$, where $f_1(t) = 2\sin(200\pi t)$ and $f_2(t) = \delta(t 0.25 \times 10^{-3})$. (2 marks)
- B) (i) Define the Fourier transform of a signal. (2 marks)
 - (ii) The rectangular pulse x(t) shown in **figure 3** is of height A, width τ and symmetrical about the time origin can be expressed as $x(t) = \begin{pmatrix} A & for & -\tau/2 \le t \le \tau/2 \\ 0 & elsewhere \end{pmatrix}$

Find

- a) the spectrum of x(t) (4 marks)
- b) sketch the spectrum of x(t) (2 marks)
- iii) An exponentially-decaying sinusoidal voltage has the form $v(t) = Ae^{-\alpha t} \sin \omega_0 t \text{ for } t \ge 0.$

Find the spectrum of this waveform. (5 marks)

iv) Use the principle of superposition to find the spectrum of the pulse in figure 4. (4 marks)



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A) For the following signal in figure 5:

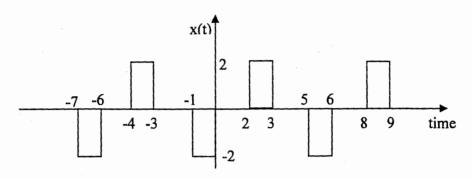


Figure 5

i) Find the Fourier series

(8 marks)

ii) Plot the spectra versus frequency, $\omega = n\omega_0$.

(4 marks)

- B) A voltage signal is modeled as the sinusoid $v(t) = 5\cos(3t + 0.5)$.
 - i) Express the signal in terms of exponential frequency components. (5 marks)
 - ii) Sketch the frequency domain representation of the signal.

(2 marks)

- C) Consider the circuit in figure 6.
 - i) Determine the ratio $\frac{v_{out}}{v_{in}} = G(j\omega)$ (3 marks)
 - ii) Determine and sketch the amplitude and phase characteristics of the circuit in figure 6. (3 marks)

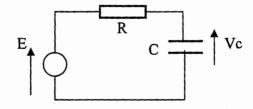


Figure 6

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FACULTY OF SCIENCE

DEPARTMENT OF ELECTRICAL & ELECTRONIC ENGINEERING

MAIN EXAMINATION MAY 2009

TITLE OF PAPER: LINEAR SYSTEMS

COURSE CODE: E352

TIME ALLOWED: THREE (3) HOURS

INSTRUCTIONS:

- 1. Answer question one and any other three questions.
- 2. Question one carries 40 marks.
- 3. Questions 2, 3, 4, and 5 carry 20 marks each.
- 4. Marks for different sections are shown in the right-hand margin

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(A) The relationship between the input x(t) and the output y(t) for a nonlinear system is given by the equation $y(x) = x^2 + x\sin(x)$. Obtain an approximate linear equation representing this system at an operating point $x_0 = 2$.

(13 marks)

- (B) An input $\mathbf{r}(t) = 1$ for $t \ge 0$ is applied to a black box with a transfer function G(s) when the initial conditions are zero. The resulting output response is $\mathbf{y}(t) = t + 0.5t^2 + (1/3)\sin(3t)$ Obtain the transfer function G(s).
- (C) (i) Why is convolution important in the analysis of linear time-invariant systems? (2marks)
 - (ii) In case of linear time-invariant state-space models what is linear transformation of states and why is it useful? (3 marks)
- (D) The transfer function of a linear system is $\frac{Y(s)}{R(s)} = \frac{10(s+3.74)}{s^2+6s+34}.$

If r(t) is a unit step input,

(i)determine the response y(t)

(10 marks)

(ii) determine the rise time, and

(3 marks)

(iii) determine the settling time for 5% tolerance..

(3 marks)

(A) A linear system is represented by the Equation

$$\dot{x} = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 0.5 \end{bmatrix} u$$

where u is a unit step.

(i) Find the matrix $\Phi(t)$

(8 marks)

(ii) For the initial conditions $x_1(0) = 1$ and $x_2(0) = 2$ find x(t).

(12 marks)

A continuous time-invariant linear system is presented by the following model

$$\dot{x} = \begin{bmatrix} 1 & 2 & 0 \\ -7 & -2 & -36 \\ -1 & 0 & -7 \end{bmatrix} x + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} u$$

$$y = \begin{bmatrix} 1 & 0.4 & 5 \end{bmatrix} x$$

Obtain the diagonal form realization of this system..

[20 marks]

Use Mason's gain rule to find the transfer function of a fuel-injection engine system model whose block diagram is shown in Figure 4. (20 marks)

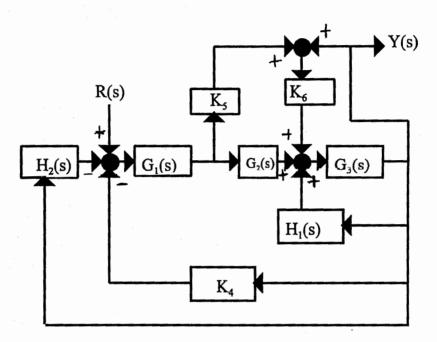


Figure 4

For an equivalent circuit of a two-transistor series voltage feedback amplifier shown in Figure 5.

(i) Use block diagram reduction method to determine the voltage gain $\frac{\mathbf{V}_o(s)}{\mathbf{V}_{in}(s)}$

(10 marks)

(ii) Determine the transfer function $\frac{\mathbf{V}_{in}(s)}{\mathbf{I}_{b1}(s)}$ representing the input impedance.

(10 marks)

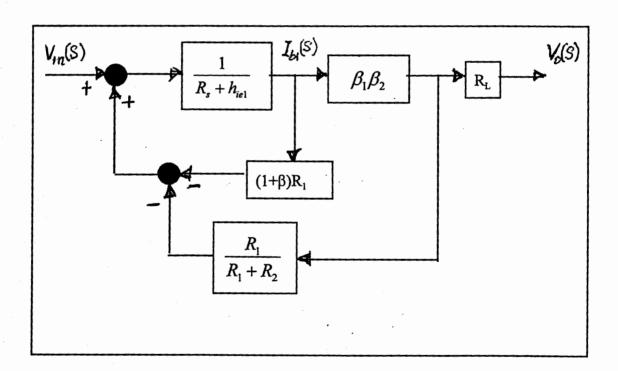


Figure 5

